

Sustainable sensing

Enabling Technology for Computational Sustainability

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IL PRESENTE MATERIALE È RISERVATO AL PERSONALE DELL'UNIVERSITÀ DI BOLOGNA E NON PUÒ ESSERE UTILIZZATO AI TERMINI DI LEGGE DA ALTRE PERSONE O PER FINI NON ISTITUZIONALI



Ambient Intelligence



Ambient Intelligence electronic environments that are sensitive and responsive to the presence of people

AmI = Ubiquitous computing + intelligent social user interfaces





Energy-Neutral Aml



Multiple Scenarios: Indoor/Outdoor Stationary/Mobile/Wearable

- No power and data cable for sensors and controls
- Easy to install (in the optimal position)
- Retrofitting is feasible and inexpensive
- Battery-powered operation \rightarrow maintenance

Energy-neutral → harvest energy from the surrounding environment and store it locally

- Photovoltaic (outdoor, indoor)
- Inductive coupling
- RF energy
- Air flow
- Motion, vibration

The Good News



- The gap between scavengers energy and requirements of digital systems is shrinking
- Exploit energy management strategies and improvements in scavenger technology
 - Overcome traditional energy management strategies (battery-driven)
- An new unified design methodology is required
 - Smart adaptation
 - Design for unreliability
 - Exploit unpredictable power sources



Sensor Node Evolution





Where are we now?





EH powered nodes





EH Subsystem architecture

- Not all are required for every application and every source
- Rectifier, DC-DC converter and MPPT are the most challenging and require a very accurate design process (coupling)
- Charger/limiter/protection consumes additional power and are often to some extent redundant.





Energy sources

Non-monotonic & Unpredictable

E.g. solar power (PV-cells)

"light"

50

0

0

P[mW]

E.g. power waveform from human walk (piezo-scavengers)





Low power design ≠ Design for neutrality

Natural progression of Energy Optimization Techniques



Hardware Design

- Conversion efficiency
- Impedance Matching
- Maximum power transferred

Software Design

- Energy Prediction,
- Scheduling & Allocation
- QoS adaptation



Aml Contexts

- GENESI genesi.di.uniroma1.it
 - Structural monitoring
- SCALOPES <u>www.scalopes.eu</u> – Video-surveillance
- SOFIA <u>www.sofia-project.eu</u>
 - Smart objects & spaces
- Sensaction-AAL
 - Auditory Biofeedback
- SMILING <u>www.smilingproject.eu</u>

- Training active exoskeleton





How hard?



Wireless Video WSNs

- Features:
 - Video acquisition analysis in real time (detection)
 - Multi Sensor
 - Data Fusion

- WSN challenges
 - High data rate → needs local processing
 - High power consumption due to
 - huge quantity of data produced in by image sensors
 - Useless processing occurring when the scenario doesn't change

Low Power HW is not enough









Multi-modal Approach



Embedded Linux Kernel 2.6.27(CPUfreq + PM framework)



Multi-level + Multi-modal

- Interaction Application / Resource Manager
- Dynamically scales processor frequencies and application features
- Reduction of the power Consumption
- Dynamic tuning of video algorithm and application
- Variable Quality of Service (FR, Accuracy)





Results

Estimated time life using three approaches (with 1000mAh battery)



Reduction of power consumption up to about 60%



Multi-ML + Distributed



17/19



Example





Results

 Camera's lifetime prolongation for the Scenario with a PIR nework for lower WOR duty cycles



Working on physical-layer Wake-up radio and system implications



Energy Generation Options

Wu

German

200

500

100

Solar + Wind + High-frequency kinetic *together* do the job + aggressive network power management 25000 LUX

Source	Power Density	
Solar	1 – 100	mW/cm ²
Vibration Capacitive	100	μW/cm³
Vibration Inductive	10 – 15	μW/cm³
Vibration Piezoelectric	300 - 500	μW/cm³
Thermoelectric	6 – 15	μW/cm³
High frequency vibration	100	μW/cm³
Ambient radio frequency	< 1	μW/cm²
Vibrational microgenerators	800 (@ kHz)	μW/cm³
Ambient airflow	1	mW/cm ²



Output current (mA)

2000

1000 Load resistance $R_{i}(\Omega)$ 5000



How hard?





Monitoring, alerting, training





Closed loop scenario: Biofeedback for rehabilitation



<u>videos</u>



Clinical validation trial



Vibro-tactile navigation system

- Add application specific strategies.
- Important factors in the perception of a tactile stimulation:
 - Vibration frequency
 - Vibration amplitude
 - Stimulation location
 - The Adaptation behavior.
- We produce stimulation through on-off pulses in a square-wave shape.
 - By changing the duty cycle of these pulses we add another control variable to the system









Bring Sensaction-AAL Home

- Extend battery lifetime
- Strategy:
 - Reduction of energy requirements:
 - Low-power node design and component selection
 - On board processing minimize wireless transmission
 - Context-aware power management
 - Reduce QoS: simplest feedback
 - Harvest energy
 - Indoor PV?
 - EM?
 - Kinetic?
 - Thermal?



Miniature PV harvesting

- WSN HW support a wide voltage supply range (usually between 1V and 4V) Tmote Sky 2,1 – 3,6 V TinyNode 584 2,4 – 3,6 V
 - TI Node 1,8 3,6V



[µsolar scavenger 10mm² PV surface: Brunelli, Benini]

- Powering sensor nodes with unregulated and variable voltage supply from the solar cell → adaptive Active-Recovery DC
 - Minimize the energy used for DC/DC or linear regulation
 - Automatically adapt duty-cycle with analog thresholds (comparators) on voltage supply
 - Optimize thresholds for MPP in low-lighting condition (no tracking at high lighting as energy is over-abundant)



Approach

- Select the desired light intensity and find the solar cell MPP
- A window (Vth1, Vth2) is defined around the MPP forcing the senor node to operate in this range of values.



Motion and Vibrations

Electrostatic



Electromagnetic





Piezoelectric

More easily implemented in standard micromachining processes
Requires a separate voltage source (such as a battery) to begin the <u>conversion cycle</u>.

 $\sim 4 \text{ mJ/cm}^3$

•Typically output AC voltages is below 1 volt in magnitude

•Not easy to implement with MEMS technologies

•The output voltage is irregular and depends on the constructions

•An overvoltage protection circuits is required

~12 mJ/cm³





Kinetic Harvester with micro-motors

Micromotors



Kinetron (NL)

Size	6,5 x 2,5
Weight	~80 g
Storage Capacitance	4700 μF
Average power (2 Hz)	206 µW
Energy per minute	12,4 mJ

6,5 x 2,5 x 2,5 cm ~80 g 4700 μF 206 μW 12,4 mJ



(10x more than piezo!)

Major challenge: Mechanical Coupling with the body



Harvesting Thermal Energy





Thermal Harvesting from Human Body

Thermal energy from human body: ~ 6 mW/cm² $P \sim 20 \ \mu W/cm^2$ Conversion efficiency at $\Delta T=5K: \sim 0.3\%$ (not a problem!) Heat dissipation from top case into air Quartz Watches: ~40 µW Movement (http://www.roachman.com/thermic/) Body heat Power storage Thermoelectric Thermal and module insulation management Back case Seiko (45µW), Citzen (14µW)

In order to obtain an operating voltage of 1.5 V, over 2000 pairs of Bi₂Te₃ thermocouples are required.

very costly using conventional module fabrication technology



Energy Generation & Storage

- One size does not fit all for generation
 - Environmental energy sources are (intrinsically) highly heterogeneous
 - Their availability strongly depends on application context
- ...and for storage
 - Major tradeoffs in density vs. peak current vs.
 # of recharge cycles vs. cost

Energy Storage Options





Putting it all together: the Smart EH Unit

Heterogeneous EH + Storage





MPPT = Maximum Power Point Tracking







Energy harvesting subsystems

- Operate independently of each other
- Each one performs MPPT
- Each one stores the collected energy in its own supercapacitor (or battery)



Energy harvesting subsystems

- Operate independently of each other
- Each one performs^{edded} system
- Each one stores the collected energy in its own supercapacitor (or battery)

Putting it all together

- Power unit with radio trigger capabilities
- •To provide the nodes with a smart power management sub-system
- Policies for power management
- Dynamic duty cycling
- Advanced wakeup/sleep mechanisms





Commercial harvesters

- PV: quite mature, with many products
 - Flexible PV materials are interesting e.g. <u>www.powerfilmsolar.com</u>
- Solution provides
 - www.enocean.com (Piezo, kinetic, solar)
 - <u>www.kinetron.com</u> (EM kinetic)
 - <u>www.micropelt.com</u> (thermal)
 - <u>www.powercast.com</u> (RF –transmission)
 - www.microstrain.com (Piezo)
- ...and many others EH forum
 - www.energyharvesting.net



Now, let's make it really hard!

Large power sinks or Ultra-small for factors



Smart Prosthetics

- Local project with INAIL:
 - Smart node based on electromiographic sensors to drive a prosthetic arm+hand
 - Embedding intelligence on board (pattern recognition)

 Motors involved... that is Watts!







"Big" Harvesters



Larry Rome, University of Pennsylvania, 2005

walking reacting with 20-38 kg inertial

5 cm up-down hip movement from

www.bionicpower.com 8-14W power from comfortable walking pace (2 devices) 1.5m/s on level ground





load generated up to 7 Watts





Up to 1-2W



Going small – In-vivo WSN

- Embedded coil and microelectronics module are hermetically sealed within a titanium package.
- Implant monitors static & dynamic forces and moments across knee

in vivo.





Current state of the art \rightarrow Inductive power coupling



Miniaturized, Integrated Storage

Cymbet's EnerChip Permits System-on-Chip Integration and Surface Mount Packaging



Image Courtesy DOE-ORNL



Micro Power Transmission

- Energy harvested from RF waves, generated by a transmitter (wireless power transmission)
- Store the energy with supercapacitor like energy buffer

Rectenna

Ant



RFID transmitter 868 MHz



Power Transfer Efficiency





Harvesting-aware Management

- Tasking aware of battery status & harvesting opportunities
 - Richer nodes take more load
 - Looking at the battery status is not enough
- Learn the energy environment





System Model



Models for application, quality/utility, system behavior Optimization problem Efficient run-time implementation



- Optimization problem: finite horizon control
 - Example: Linear program for sensing/transmitting optimization

	maximize $(\lambda - \mu)$ subject to:	(14)
Rate of acquisition	$s_1(t+k\cdot L) \ge \lambda$	$\forall 0 \leq k < N$
Memory usage	$M(t+N) \le \mu$	
Stored energy	$E_C(t + k \cdot L) = E_C(t) + \sum_{j=0}^{k-1} \widetilde{E}(t,j) - E_C(t,j) - $	
	$-\sum_{j=0}^{k-1} \left(L \cdot \begin{bmatrix} 0.1 & 0.9 \end{bmatrix} \cdot \mathbf{S}(t+j \cdot L) \right) \ge 0$	$\forall 1 \leq k \leq N$
Used memory	$M(t + k \cdot L) = M(t) + $	
	$+L\sum_{j=0}^{k-1} \begin{bmatrix} 1 & -1 \end{bmatrix} \cdot \mathbf{S}(t+j \cdot L) \ge 0$	$\forall 1 \leq k \leq N$
Final stored energy	$E_C(t+N\cdot L) \ge E_C(t) - 150$	





Toward the Micro Smart Grid



Heterogeneous, Collaborative EH + Power transmission



An exciting future...

